Homework 6.

Problem 1. 10 points. Sylvester formula – dipole/quadrupole

For an uncoupled transverse motion with constant energy and Hamiltonian of a bending magnet with quadrupole term (e.g. field gradient):

$$\tilde{h}_{n} = \frac{p_{x}^{2} + p_{y}^{2}}{2} + f \frac{x^{2}}{2} + g \frac{y^{2}}{2};$$

$$f = \left[K_{o}^{2} - K_{1}\right]; g = -K_{1}; K_{o} = -\frac{e}{p_{o}c}B_{y}; K_{1} = -\frac{e}{p_{o}c}\frac{\partial B_{y}}{\partial x}$$

- (a) Define all cases for eigen values of D.
- (b) Use Sylvester formula for one-dimensional motions (x and y) when $f \neq 0$; $g \neq 0$; (non-degenerated cases) and write explicit form of the 2x2 transport matrices.
- (c) Consider a case of pure quadrupole: $K_0 = 0$, no bending
- (d) Do the same as above using 4x4 matrix formulation (2D case) and show that results are identical

Problem 2. 10 points. Sylvester formula, SQ-quadrupole

For a coupled transverse motion with constant energy and Hamiltonian of a SQquadrupole:

$$\tilde{h}_n = \frac{p_x^2 + p_y^2}{2} + Nxy; \qquad N = \frac{e}{p_o c} \frac{\partial B_x}{\partial x}$$

- (a) Use Sylvester formula and find matrix of SQ-quadrupole.
- (b) Consider a "standard approach" turn coordinates 45-degrees (use rotation matrix), to turn SQ-quad into a "normal". Then make the product of 45-degree turn, quad matrix, -45 degrees turn. Show that the matrix is the same as in case (a).

Note: for point (b), consider a rotation is around z-axis: it will rotate x,y and p_x,p_y:

$$\begin{pmatrix} x^{1} \\ p_{x}^{1} \\ y^{1} \\ p_{y}^{1} \end{pmatrix} = R \begin{pmatrix} x \\ p_{x} \\ y \\ p_{y} \end{pmatrix} = \begin{bmatrix} I \cdot \cos \varphi & I \cdot \sin \varphi \\ -I \cdot \sin \varphi & I \cdot \cos \varphi \end{bmatrix} \begin{pmatrix} x \\ p_{x} \\ y \\ p_{y} \end{pmatrix}; I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Thus

$$x^{1} = x\cos\varphi + y\sin\varphi; \quad y^{1} = -x\sin\varphi + y\cos\varphi$$
$$p_{x}^{1} = p_{x}\cos\varphi + p_{y}\sin\varphi; \\ p_{y}^{1} = -p_{x}\sin\varphi + p_{y}\cos\varphi$$

Do not forget that you need inverse matrix of R as well.

In rotated coordinates with $\varphi = \pi / 2$ the Hamiltonian will have a decoupled form of one in quadrupole and you easily can calculate the matrix M_Q.. Finally, you need to rotate back to initial coordinates. $M_{SO} = R^{-1} \cdot M_O \cdot R$